

SYSTEMATIC MEASURES OF BIOLOGICAL NETWORKS, PART I: INVARIANT MEASURES AND ENTROPY

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ABSTRACT. This paper is Part I of a two-part series devoting to the study of systematic measures in a complex biological network modeled by a system of ordinary differential equations. As the mathematical complement to our previous work [31] with collaborators, the series aims at establishing a mathematical foundation for characterizing three important systematic measures: degeneracy, complexity and robustness, in such a biological network and studying connections among them. To do so, we consider in Part I stationary measures of a Fokker-Planck equation generated from small white noise perturbations of a dissipative system of ordinary differential equations. Some estimations of concentration of stationary measures of the Fokker-Planck equation in the vicinity of the global attractor are presented. Relationship between differential entropy of stationary measures and dimension of the global attractor is also given.

1. INTRODUCTION

The concept of modular biology has been proposed and extensively investigated in the past several decades. In a complex biological network, modules in cells are created by interacting molecules that function in a semi-autonomous fashion and they are functionally correlated. To better understand the interactions between modules in a complex biological network, it is necessary to quantitatively study systematic properties such as degeneracy, robustness, complexity, redundancy, and evolvability.

Emerged from early studies of brain functions [14], notions of degeneracy and complexity were first introduced in neural networks in [43], and the robustness was studied in [29, 30] for systems with performance functions. Roughly speaking, in a cellular network or a neural network degeneracy measures the capacity of elements that are structurally different to perform the same function, structural complexity measures the magnitude of functional integration and local segregation of sub-systems, and the robustness measures the capacity of performing similar function under perturbation. These systematic measures are known to be closely related. Indeed, it has already been observed via numerical simulations for neural networks that high degeneracy not only yields high robustness, but also it is accompanied by an increase in structural complexity [44].

As increasing biological phenomena are being observed, attentions were also paid toward quantitative studies of systematic measures in biological networks. For instance, numerical simulations reveal connections between degeneracy and complexity in artificial chemistry binding systems [7]; and also conclude that degeneracy underlies the presence of long range correlation in complex networks [10, 11]. Features like regulation and robustness of biochemical networks of signal transduction have also been studied quantitatively in [30, 40]. Degeneracy, complexity and robustness were quantified for neural networks by making use of testing noise injections into the networks in [44]. However, it was later remarked in the review article [13] that “degeneracy is a ubiquitous property of biological systems

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at all levels of organization, the concept has not yet been fully incorporated into biological thinking, ... because of the lack of a general evolutionary framework for the concept and the absence of a theoretical analysis". Recently, quantification of degeneracy, complexity and robustness in biological networks modeled by systems of ordinary differential equations was made in the authors' joint work [31] with Dwivedi, Huang and Kemp. The goal of that study is precisely to extend the concept of degeneracy to an evolutionary biological network and to establish its connections with complexity and robustness.

The present work, consisting of two parts, serves as the mathematical complement of our previous work [31], aiming at establishing a mathematical foundation of degeneracy, complexity and robustness in a complex biological network modeled by a system of ordinary differential equations.

This mathematical foundation is based on the theory of stochastic differential equations. In particular, considering testing white noise perturbations to a biological network is important in the quantification of its systematic measures because characterizations of degeneracy and complexity rely on the functional connections among modules of the network and such connections can be activated by injecting external noises, similarly to the case of neural systems [31, 44].

To be more precise, consider a biological network modeled by the following system of ordinary differential equations (ODE system for short):

$$(1.1) \quad x' = f(x), \quad x \in \mathbb{R}^n,$$

where f is a C^1 vector field on \mathbb{R}^n , called *drift field*. Under additive white noise perturbations σdW_t , we obtain the following system of stochastic differential equations (SDE system for short):

$$(1.2) \quad dX = f(X)dt + \epsilon\sigma(x)dW_t, \quad X \in \mathbb{R}^n,$$

where W_t is the standard m -dimensional Brownian motion, ϵ is a small parameter lying in an interval $(0, \epsilon^*)$, and σ , called a *noise matrix*, is an $n \times m$ matrix-valued, bounded, C^1 function on \mathbb{R}^n for some positive integer $m \geq n$, such that $\sigma(x)\sigma^\top(x)$ is everywhere positive definite in \mathbb{R}^n . We denote the collection of such noise matrices by Σ . Under certain dissipation condition (e.g., the existence of Lyapunov function corresponding to (1.2) assumed in this paper), the SDE system (1.2) generates a diffusion process in \mathbb{R}^n which admits a transition probability kernel $P^t(x, \cdot)$, $t \geq 0$, $x \in \mathbb{R}^n$, such that for each $x \in \mathbb{R}^n$, $P^t(x, \cdot)$ is a probability measure and for each Borel set $B \subset \mathbb{R}^n$, $P^t(x, B)$ measures the probability of the stochastic orbit starting from x entering the set B at time t . An *invariant probability measure of the diffusion process* associated with (1.2) is the left invariant of $P^t(x, \cdot)$ such that

$$(\mu_\epsilon P^t)(\cdot) = \int_{\mathbb{R}^n} P^t(x, \cdot) d\mu_\epsilon = \mu_\epsilon(\cdot), \quad t \geq 0.$$

An invariant probability measure associated with (1.2) is necessarily a stationary measure of the Fokker-Planck equation associated with (1.2). In general, a stationary measure can be regarded as a "generalized invariant measure" if the diffusion process fails to admit an invariant measure.

By injecting external fluctuation $\epsilon\sigma dW_t$ into the network (1.1), the connections among different modules of the network are activated. Assuming the existence of a stationary measure μ_ϵ of the Fokker-Planck equation associated with (1.2) for each $\epsilon \in (0, \epsilon^*)$, the mutual information among any two modules (coordinate subspaces) X_1, X_2 can be defined using the margins μ_1, μ_2 of μ_ϵ with respect to X_1, X_2 , respectively. Such mutual information can then be used to quantify degeneracy and complexity, and further to examine their connections with dynamical quantities like robustness.

Such a mathematical foundation for degeneracy, complexity, and robustness in a biological network relies on a quantitative understanding of the stationary measures μ_ϵ particularly with respect to their concentrations. This is in fact the main subject of this part of the series.

A well-known approach to study the invariant probability measure is the classical large-deviation theory (or Freidlin-Wentzell theory). The probability that the trajectory of (1.2) stays in the neighborhood of any absolutely continuous function can be calculated explicitly by Girsanov's theorem. This leads to some estimates of tails of stationary measures, or the first exit time of a stochastic orbit etc (see e.g. [12, 17, 28]). For instance, it is shown in [17] that for any set $P \subset \mathbb{R}^n$ that does not intersect with any attractor of (1.1), there exists a constant $V_0 > 0$ such that

$$(1.3) \quad \lim_{\epsilon \rightarrow 0} \epsilon^2 \log \mu_\epsilon(P) = -V_0.$$

In particular, the limit

$$(1.4) \quad - \lim_{\epsilon \rightarrow 0} \epsilon^2 \log \frac{d\mu_\epsilon(x)}{dx} := V(x),$$

if exists, is called the *quasi-potential function*.

One limitation of the large deviation theory is that usually it can only estimate the probability of rare events, which corresponds to the tails of stationary measures. In many applications, more refined analysis is based on the assumption that μ_ϵ can be approximated by a Gibbs measure, i.e., μ_ϵ admits a density function u_ϵ such that

$$(1.5) \quad u_\epsilon(x) \approx \frac{1}{K} e^{-V(x)/\epsilon^2},$$

where $V(x)$ is the quasi-potential function [20, 39, 41, 42]. However, this assumption is difficult to verify in general as it requires high regularity of the quasi-potential function. Rigorous results are only known for some simple systems [8, 9, 33].

To understand connections among degeneracy, complexity, and robustness, we need to measure the effects of stochastic perturbations in (1.2) at the same order as ϵ . To make such estimation rigorously, we will adopt the level set method recently introduced in [26, 27] for stationary probability measures of the Fokker-Planck equation associated with (1.2) (see Section 2).

In this part of the series, we will mainly apply the level set method to obtain estimates on the concentrations of invariant measures μ_ϵ with respect to a fixed $\sigma \in \Sigma$. Our main results of the paper lie in the following three categories.

- a) *Concentration in the vicinity of the global attractor \mathcal{A}* : We will show in Theorem 3.2 that for any $0 < \delta \ll 1$ there exists a constant $M > 0$ such that

$$\mu_\epsilon(\{x : \text{dist}(x, \mathcal{A}) \leq M\epsilon\}) \geq 1 - \delta.$$

We will also show in Theorem 3.3 that for any $\alpha \in (0, 1)$,

$$\lim_{\epsilon \rightarrow 0} \mu_\epsilon(\{x : \epsilon^{1+\alpha} \leq \text{dist}(x, \mathcal{A}) \leq \epsilon^{1-\alpha}\}) = 1.$$

- b) *Mean square displacement*: We will show in Theorem 3.4 under certain conditions that there exist constants $V_1, V_2 > 0$ such that

$$V_1 \epsilon^2 \leq V(\epsilon) \leq V_2 \epsilon^2,$$

where

$$V(\epsilon) = \int_{\mathbb{R}^n} \text{dist}^2(x, \mathcal{A}) d\mu_\epsilon(x).$$

- c) *Entropy-dimension relationship*: We will show in Theorem 4.1 that if the global attractor \mathcal{A} is regular, then

$$\liminf_{\epsilon \rightarrow 0} \frac{\mathcal{H}(\mu_\epsilon)}{\log \epsilon} \geq n - d$$

where $\mathcal{H}(\mu_\epsilon)$ is the differential entropy of μ_ϵ and d is the Minkowski dimension of \mathcal{A} .

The paper is organized as follows. Section 2 is a preliminary section in which we mainly review some results and the level set method from [25–27] on Fokker-Planck equations. Concentrations of stationary measures are studied in Section 3. We derive the entropy-dimension relationship in Section 4.

2. PRELIMINARY

In this section, we will review some notions and known results about dissipative dynamical systems and Fokker-Planck equations including global attractors, Lyapunov functions, and the existence and uniqueness of stationary measures. We will also recall a Harnack inequality to be used later.

2.1. Dissipation and global attractor. We note that the system (1.1) generates a local flow on \mathbb{R}^n , which we denote by ϕ^t . For $B \subset \mathbb{R}^n$, we denote $\phi^t(B) = \{\phi^t(x) : x \in B\}$. A set $A \subset \mathbb{R}^n$ is said to be *invariant* with respect to (1.1) or ϕ^t if ϕ^t extends to a flow on A and $\phi^t(A) \subset A$ for any $t \in \mathbb{R}$.

System (1.1) or ϕ^t is said to be *dissipative* if ϕ^t , $t \geq 0$, is a positive semi-flow on \mathbb{R}^n and there exists a compact subset K of \mathbb{R}^n with the property that for any $\xi \in \mathbb{R}^n$ there exists a $t_0(\xi) > 0$ such that $\phi^t(\xi) \in K$ as $t \geq t_0(\xi)$. It is well-known that if ϕ^t is dissipative, then it must admit a *global attractor* \mathcal{A} , i.e., \mathcal{A} is a compact subset of \mathbb{R}^n which attracts any bounded set in \mathbb{R}^n in the sense that $\lim_{t \rightarrow +\infty} \text{dist}(\phi^t(K), \mathcal{A}) = 0$ for every bounded set $K \subset \mathbb{R}^n$, where $\text{dist}(A, B)$ denote the Hausdorff semi-distance from a bounded set A to a bounded set B in \mathbb{R}^n . The global attractor \mathcal{A} of ϕ^t , if exists, must be unique and invariant with respect to ϕ^t . In fact, ϕ^t is dissipative if and only if it is a semi-flow admitting a global attractor. Moreover, dissipation of ϕ^t can be guaranteed by the existence of a *Lyapunov function* U of (1.1), i.e., $U \in C^1(\mathbb{R}^n)$ is a non-negative function such that $U(x) < \sup_{x \in \mathbb{R}^n} U(x)$, $x \in \mathbb{R}^n$, and there exist a compact set $K \subset \mathbb{R}^n$ and a constant $\gamma > 0$, called a *Lyapunov constant*, such that

$$f(x) \cdot \nabla U(x) \leq -\gamma, \quad x \in \mathbb{R}^n \setminus K.$$

The global attractor \mathcal{A} of (1.1) is said to be a *strong attractor* if there is a connected open neighborhood \mathcal{N} of \mathcal{A} with C^2 boundary, called *isolating neighborhood*, such that i) $\omega(\mathcal{N}) = \mathcal{A}$ and ii) $f(x) \cdot \nu(x) < 0$ for each $x \in \partial\mathcal{N}$, where $\nu(x)$ is the outward normal vector of \mathcal{N} at x and $\omega(B) := \bigcap_{\tau \geq 0} \overline{\{\phi^t(B) : t \geq \tau\}}$ is the ω -limit set of a bounded set $B \subset \mathbb{R}^n$. It is clear that \mathcal{A} is a strong attractor of (1.1) if there exists a *strong Lyapunov function* in a connected open set $S \subseteq \mathbb{R}^n$ containing \mathcal{A} , i.e., $\nabla U(x) \neq 0$, $x \in S \setminus \mathcal{A}$, and there is a constant $\gamma_0 > 0$ such that

$$f(x) \cdot \nabla U(x) \leq -\gamma_0 |\nabla U(x)|^2, \quad x \in S \setminus \mathcal{A}.$$

We again refer the constant γ_0 above to as the *Lyapunov constant* of U .

2.2. Fokker-Planck equation and stationary measures. If the transition probability kernel $P^t(x, \cdot)$ of the SDE system (1.2) admits a probability density function $p^t(x, z)$, i.e.,

$$P^t(x, B) = \int_B p^t(x, z) dz$$

for any Borel set $B \subset \mathbb{R}^n$, then for any measurable, non-negative function $\xi(x)$ with $\int_{\mathbb{R}^n} \xi(x) dx = 1$, $u_\epsilon(x, t) = \int_{\mathbb{R}^n} p^t(z, x) \xi(z) dz$ characterizes the time evolution of the probability density function. Formally, $u_\epsilon(x, t)$ satisfies the following Fokker-Planck equation (FPE for short) :

$$(2.1) \quad \begin{cases} \frac{\partial u_\epsilon(x, t)}{\partial t} = \frac{1}{2} \epsilon^2 \sum_{i,j=1}^n \partial_{ij} (a_{ij}(x) u_\epsilon(x, t)) - \sum_{i=1}^n \partial_i (f_i(x) u_\epsilon(x, t)) := L_\epsilon u_\epsilon(x, t), \\ \int_{\mathbb{R}^n} u_\epsilon(x, t) dx = 1, \end{cases}$$

where $(a_{ij}(x)) := A(x) := \sigma(x)\sigma^\top(x)$ is an $n \times n$, everywhere positive definite, matrix-valued C^1 function, called *diffusion matrix*. The operator L_ϵ is called *Fokker-Planck operator*.

Among solutions of the Fokker-Planck equation, of particular importance are the *stationary solutions*. For any connected open subset $S \subset \mathbb{R}^n$, stationary solutions on S satisfy the stationary Fokker-Planck equation

$$(2.2) \quad L_\epsilon u_\epsilon(x, t) = 0, \quad \int_S u_\epsilon(x, t) dx = 1, \quad u \geq 0.$$

More generally, on any connected open subset $S \subset \mathbb{R}^n$, a *stationary measure* of the Fokker-Planck equation is a probability measure μ_ϵ satisfying

$$\int_S \mathcal{L}_\epsilon h(x) d\mu_\epsilon = 0, \quad \forall h(x) \in C_0^\infty(S),$$

where

$$\mathcal{L}_\epsilon = \frac{1}{2}\epsilon^2 \sum_{i,j=1}^n a_{ij}(x)\partial_{ij} + \sum_{i=1}^n f_i(x)\partial_i$$

is the *adjoint Fokker-Planck operator*.

If u_ϵ is a stationary solution of the Fokker-Planck equation (2.1), then $u_\epsilon dx$ is clearly a stationary measure. Conversely, it follows from the regularity theory of Fokker-Planck equation [3] and standard regularity theory of elliptic equation that a stationary measure of Fokker-Planck equation (2.1) must admit a density function which is a strictly positive, classical stationary solution of the Fokker-Planck equation. Note that a classical solution means a solution that has enough regularity to be plugged into the original differential equation.

An invariant measure of the diffusion process generated by (1.2), or equivalently, of the transition probability kernel P^t , is necessarily a stationary measure of the corresponding Fokker-Planck equation (2.1). The converse needs not be true in general. However, stationary measures considered in this paper are in fact invariant measures of the diffusion process generated by (1.2).

The existence and estimates of stationary measures of (2.1) are related to Lyapunov-like functions associated with it. For the sake of generality, we consider a connected open set $S \subseteq \mathbb{R}^n$. A non-negative function $U \in C(S)$ is said to be a *compact function* if (i) $U(x) < \rho_M$, $x \in S$; and (ii) $\lim_{x \rightarrow \partial S} U(x) = \rho_M$, where $\rho_M = \sup_{x \in S} U(x)$ is called the *essential upper bound of U* . In the case $S = \mathbb{R}^n$, $x \rightarrow \partial S$ simply means that $x \rightarrow \infty$. It is obvious that Lyapunov and strong Lyapunov functions defined in the previous subsection are all compact functions on \mathbb{R}^n .

For a compact function defined on S and for each $\rho \in [0, \rho_M)$, we denote $\Omega_\rho(U) = \{x \in S : U(x) < \rho\}$ as the ρ -*sublevel set* of U and $\Gamma_\rho(U) = \{x \in S : U(x) = \rho\}$ as the ρ -*level set* of U .

Let U be a compact C^2 function on a connected open set $S \subset \mathbb{R}^n$ with upper bound ρ_M . For a fixed $\epsilon \in (0, \epsilon^*)$, U is called a *Lyapunov function associated with (2.1)* (on S) if there are constants $\rho_m, \gamma > 0$, referred to as *an essential lower bound, the Lyapunov constant of U* , respectively, such that

$$\mathcal{L}_\epsilon U(x) < -\gamma, \quad x \in S \setminus \Omega_{\rho_m}(U).$$

U is called a *weak Lyapunov function* (on S) associated with equation (2.1) if there is a constant ρ_m , still referred to as an essential lower bound of U , such that

$$\mathcal{L}_\epsilon U(x) \leq 0, \quad x \in S \setminus \Omega_{\rho_m}(U).$$

If $U(x)$ is a Lyapunov function (resp. weak Lyapunov function) associated with (2.1) for each $\epsilon \in (0, \epsilon^*)$ and the essential lower bound and Lyapunov constant is independent of ϵ , then $U(x)$ is called a *uniform Lyapunov function* (resp. *uniform weak Lyapunov function*) associated with the family (2.1) on $(0, \epsilon^*)$.

It is easy to see that a uniform Lyapunov function associated with the family (2.1) on $(0, \epsilon^*)$ must be a Lyapunov function for the ODE system (1.1). Consequently, if the family (2.1) on $(0, \epsilon^*)$ admits a uniform Lyapunov function, then the ODE system (1.1) must be dissipative and hence admits a global attractor.

There has been extensive studies on the existence and uniqueness of stationary measures of Fokker-Planck equation (2.1) (see [4, 5, 27] and references therein). While stationary measures of a Fokker-Planck equation in a bounded domain of \mathbb{R}^n always exist, the existence of such in the entire space (i.e. $S = \mathbb{R}^n$) necessarily require certain dissipation conditions at infinity which is more or less equivalent to the existence of a Lyapunov function.

The following theorem follows from the main result of [5, 27] and the standard regularity theory of elliptic equations.

Theorem 2.1. *If the family \mathcal{L}_ϵ , $\epsilon \in (0, \epsilon^*)$, admits an unbounded uniform Lyapunov function, then for each $\epsilon \in (0, \epsilon^*)$, the corresponding Fokker-Planck equation (2.1) has a unique stationary measure μ_ϵ on \mathbb{R}^n . Moreover, $d\mu_\epsilon(x) = u_\epsilon(x)dx$ for a classical stationary solution u_ϵ of (2.1).*

2.3. Level set method and measure estimates. The following two theorems are the main ingredient of the level set method introduced in [26].

Theorem 2.2. (Integral identity, Theorem 2.1, [26]) *For a given $\epsilon \in (0, \epsilon^*)$, let $u = u_\epsilon$ be a stationary solution of (2.1). Then for any Lipschitz domain $S \subset \mathbb{R}^n$ and a function $F \in C^2(S)$ having constant value on ∂S ,*

$$(2.3) \quad \begin{aligned} \int_S (\mathcal{L}_\epsilon F(x))u(x)dx &= \int_S \left(\sum_{i,j=1}^n \frac{1}{2}\epsilon^2 a_{ij}(x)\partial_{ij}^2 F(x) + \sum_{i=1}^n f_i(x)\partial_i F(x) \right) u(x)dx \\ &= \int_{\partial S} \left(\sum_{i=1}^n \sum_{j=1}^n \frac{1}{2}\epsilon^2 a_{ij}(x)\partial_i F(x)\nu_j \right) u(x)ds \end{aligned}$$

where $\{\nu_j\}_{j=1}^n$ denotes the unit outward normal vectors.

In applying Theorem 2.2 to study stationary solutions of a Fokker-Planck equation, one typically considers F as a Lyapunov function $U(x)$ and S as a sublevel set $\Omega_\rho(U) = \{x \in \mathbb{R}^n : U(x) < \rho\}$. When $\nabla U(x) \neq 0$ on the level set $\Gamma_\rho(U) = \{x \in \mathbb{R}^n : U(x) = \rho\}$, we note that $\partial\Omega_\rho(U) = \Gamma_\rho(U)$.

Theorem 2.3. (Derivative formula, Theorem 2.2, [26]) *Let μ be a Borel probability measure with density function $u \in C(\mathbb{R}^n)$ and U be a C^1 compact function on \mathbb{R}^n such that $\nabla U(x) \neq 0$, $x \in \Gamma_\rho(U)$ for all ρ lying in an interval (ρ_1, ρ_2) . Then*

$$\frac{\partial}{\partial \rho} \int_{\Omega_\rho(U)} u(x) dx = \int_{\Gamma_\rho(U)} \frac{u(x)}{|\nabla U(x)|} ds, \quad \rho \in (\rho_1, \rho_2).$$

Let μ_ϵ be a stationary measures of the Fokker-Planck equation (2.1). Then as shown in [26, 27], Theorems 2.2, 2.3 yield the following estimates concerning μ_ϵ in the presence of a Lyapunov function.

Lemma 2.1. (Theorem A b), [26]) *Assume that (2.1) admits a Lyapunov function U with essential lower, upper bound ρ_m, ρ_M , respectively, that satisfies $\nabla U(x) \neq 0$, $x \in \Gamma_\rho$ for almost every $\rho \in [\rho_m, \rho_M)$. Then for any function $H(\rho) \in L^1_{loc}([\rho_m, \rho_M))$ with*

$$H(\rho) \geq \frac{1}{2}\epsilon^2 \sum_{i,j=1}^n a_{ij}(x) \partial_{x_i} U(x) \partial_{x_j} U(x), \quad x \in \Gamma_\rho,$$

one has

$$\mu_\epsilon(\Omega_{\rho_M}(U) \setminus \Omega_\rho(U)) \leq e^{-\gamma \int_{\rho_m}^\rho \frac{1}{H(t)} dt}, \quad \rho \in [\rho_m, \rho_M),$$

where $\gamma > 0$ is the Lyapunov constant of U .

Lemma 2.2. (Theorem A c), [26]) *Assume that (2.1) admits a weak Lyapunov function U in a connected open set $S \subseteq \mathbb{R}^n$ with essential lower, upper bound ρ_m, ρ_M , respectively. Also assume that (a_{ij}) is everywhere positive definite in S . Then for any two positive continuous functions $H_1(\rho), H_2(\rho)$ satisfying*

$$H_1(\rho) \leq \frac{1}{2}\epsilon^2 \sum_{i,j=1}^n a_{ij}(x) \partial_i U(x) \partial_j U(x) \leq H_2(\rho), \quad x \in \Gamma_\rho(U),$$

one has

$$\mu_\epsilon(\Omega_{\rho_M}(U) \setminus \Omega_{\rho_m}(U)) \leq \mu_\epsilon(\Omega_\rho(U) \setminus \Omega_{\rho_m}(U)) e^{\int_\rho^{\rho_M} \frac{1}{H(s)} ds}, \quad \rho \in (\rho_m, \rho_M),$$

where $\tilde{H}(\rho) = H_1(\rho) \int_{\rho_m}^\rho H_2^{-1}(s) ds$.

2.4. Hanack inequality. We recall the following Harnack inequality from [18].

Lemma 2.3. *Consider an elliptic operator*

$$Lu(x) = \sum_{i,j=1}^n \partial_i(a_{ij}(x) \partial_j u(x)) + \sum_{i=1}^n \partial_i(b_i(x) u(x)) + \sum_{i=1}^n c_i(x) \partial_i u(x) + d(x) u(x)$$

in a domain $\Omega \subset \mathbb{R}^n$. Let λ and Λ be two constants depend on matrix $\{a_{ij}(x)\}$ such that

$$\sum_{i,j=1}^n a_{ij}(x) \zeta_i \zeta_j \geq \lambda |\zeta|^2$$

and

$$\sum_{i,j=1}^n |a_{ij}(x)|^2 \leq \Lambda^2.$$

Let ν be a constant such that

$$\lambda^{-2} \sum_{i=1}^n (|b_i(x)|^2 + |c_i(x)|^2 + \lambda^{-1} |d(x)|) \leq \nu^2.$$

Then for any ball $B_{4R}(y) \subset \Omega$, we have

$$\sup_{x \in B_{4R}(y)} u(x) \leq C \inf_{x \in B_R(y)} u(x)$$

where $C \leq C_0(n)^{(\Lambda/\lambda + \nu R)}$.

3. CONCENTRATION OF STATIONARY MEASURES

We make the following standard hypothesis:

H⁰) System (1.1) is dissipative and there exists a strong Lyapunov function $W(x)$ with respect to an isolating neighborhood $S := \mathcal{N}$ of the global attractor \mathcal{A} such that

$$W(x) \geq L_1 \text{dist}^2(x, \mathcal{A}), \quad x \in \mathcal{N}$$

for some $L_1 > 0$.

Remark 3.1. When \mathcal{A} is an equilibrium or a limit cycle, the stable foliation theorem asserts that a neighborhood \mathcal{N} of \mathcal{A} can be taken as a ball, and consequently $W(x)$ can be taken as $\text{dist}(x, \mathcal{A})^2$.

When noises are added to the ODE system (1.1), our theory requires characterizations and estimates of stochastic quantities such as mean square displacement and entropy-dimension formula of stationary measures of the Fokker-Planck equation (2.1) associated with the SDE system (1.2). It turns out that, for these quantities to be well-defined, the following condition on the stationary measures of (2.1) is needed:

H¹) For each $\epsilon \in (0, \epsilon^*)$, the Fokker-Planck equation (2.1) admits a unique stationary measure μ_ϵ such that

$$\lim_{\epsilon \rightarrow 0} \frac{\mu_\epsilon(\mathbb{R}^n \setminus \mathcal{N})}{\epsilon^2} = 0,$$

and moreover, there are constants $p, R_0 > 0$ such that

$$\mu_\epsilon(\{x : |x| > r\}) \leq e^{-\frac{rp}{\epsilon^2}}$$

for all $r > R_0$ and all $\epsilon \in (0, \epsilon^*)$.

Throughout the rest of the paper, for any fixed $\epsilon \in (0, \epsilon^*)$, we let μ_ϵ denote the unique stationary probability measure of (1.2) or the stationary measure of (2.1) and let $u_\epsilon(x)$ or, when it does not cause confusion, $u(x)$ stand for the (classical) stationary solution of equation (2.2), which is the density function of μ_ϵ .

To estimate these stochastic quantities mentioned above rigorously, it is essential to perform estimates on the concentration of u_ϵ both near and away from \mathcal{A} . In Section 3.1, we will conduct estimates on the local concentration of μ_ϵ in the vicinity of \mathcal{A} by making use of assumption **H⁰**) and give estimates of the tails of μ_ϵ by providing a sufficient condition which ensures the validity of the condition **H¹**).

We remark that the estimation in Section 3.1 only provides one of many approaches to verify **H⁰**) and **H¹**). Essentially **H¹**) assumes that μ_ϵ has sufficient concentration on an isolating neighborhood such that we can focus on the local analysis in the vicinity of the global attractor. Such concentration is satisfied by many problems in applications, although it may be difficult to give generic sufficient conditions. In particular, the quasi-potential function defined in (1.4), if exists, leads to the desired concentration of μ_ϵ immediately. If a quasi-potential function as in (1.4) exists and is differentiable, then it is a Lyapunov function of (1.1) [17]. This provides an alternative way of verifying **H⁰**). For results regarding high regularity of the quasi-potential function, see [8, 9].

Many biological models, including biochemical oscillation systems [45], genetic circuits [46], gene regulatory networks [24], cell cycle network [34], and genetic switch systems [32], are known to have similar quasi-potential landscape, hence **H¹**) is satisfied by these systems. Also see [1, 47] for theoretical studies of quasi-potential functions in biological systems and [22, 38, 47, 48] for numerical computation methods of the quasi-potential function.

3.1. Estimating tails of stationary measures. The purpose of this subsection is to provide an alternative way to verify assumption \mathbf{H}^0) and \mathbf{H}^1). This is important in applications as rigorously verifying the quasi-potential landscape may be difficult for some models. Instead of using the quasi-potential function, we use a suitable Lyapunov function of system (1.1) to facilitate our study. To characterize the property of the desired Lyapunov function, the following definitions are necessary.

A compact function U on a connected open set $S \subset \mathbb{R}^n$ is said to be of the class \mathcal{B}^* in S if there is a constant $p > 0$ and a function $H(\rho) \in L^1_{loc}([\rho_0, \rho_M])$ such that

$$H(\rho) \geq |\nabla U(x)|^2, \quad x \in \Gamma_\rho(U)$$

and

$$\int_{\rho_0}^{\rho} \frac{1}{H(s)} ds \geq |x|^p, \quad x \in \Gamma_\rho(U)$$

for all $\rho \in (\rho_0, \rho_M)$, where $\rho_0 = \inf_{x \in S} U(x)$.

Remark 3.2. According to the definition, a compact function $U(x)$ is of class \mathcal{B}^* in \mathbb{R}^n if (i) $U(x)$ has bounded first order derivative and (ii) $\lim_{|x| \rightarrow \infty} \frac{U(x)}{|x|^p} > 0$ for some $p > 0$. We will show that when (2.1) admits a class \mathcal{B}^* Lyapunov function, its stationary measure has an exponential tail. One example of class \mathcal{B}^* function will be given at the end of this subsection.

We will estimate the tails of stationary measures of (2.1) by dividing $\mathbb{R}^n \setminus \mathcal{N}$ into two regions: a neighborhood \mathcal{N}_∞ of ∞ in \mathbb{R}^n , i.e., the complement of a sufficiently large compact set, and the intermediate region \mathcal{N}_* between \mathcal{N}_∞ and \mathcal{N} . We make the following hypothesis:

\mathbf{H}^2) There is a positive function $U \in C^2(\mathbb{R}^n \setminus \mathcal{A})$ satisfying the following properties:

- i) $\lim_{x \rightarrow \infty} U(x) = \infty$;
- ii) There exists a constant $\rho_m > 0$ such that U is a uniform Lyapunov function of the family (2.1) of class \mathcal{B}^* in $\mathcal{N}_\infty =: \mathbb{R}^n \setminus \Omega_{\rho_m}(U)$;
- iii) There exists a constant $\bar{\rho}_m \in (0, \rho_m)$ such that U is a uniform weak Lyapunov function of the family (2.1) in $\mathcal{N}_* =: \mathbb{R}^n \setminus \mathcal{N}_\infty \setminus \Omega_{\bar{\rho}_m}(U) = \Omega_{\rho_m}(U) \setminus \Omega_{\bar{\rho}_m}(U)$;
- iv) $\nabla U(x) \neq 0, x \in \mathbb{R}^n \setminus \Omega_{\bar{\rho}_m}(U)$;
- v) $\Omega_{\bar{\rho}_m}(U) \subset \mathcal{N}$.

Remark 3.3. 1) We note that when \mathbf{H}^2) holds, Theorem 2.1 asserts the existence of a unique stationary measure of (2.1) for each $\epsilon \in (0, \epsilon_*)$.

2) With the hypotheses \mathbf{H}^0), \mathbf{H}^2), the ODE system (1.1) is dissipative in \mathcal{N}_∞ , strongly dissipative in \mathcal{N} , and remains dissipative in \mathcal{N}_* but with small dissipation rate proportional to ϵ^2 .

3) The purpose of introducing \mathbf{H}^2) is to give a Lyapunov function-based sufficient condition of \mathbf{H}^0) and \mathbf{H}^1). Except in this subsection, our estimates are based only on \mathbf{H}^0) and \mathbf{H}^1).

We first estimate the concentration of stationary measures of (2.1) in the region \mathcal{N}_∞ , which verifies the second part of \mathbf{H}^1).

Proposition 3.1. *If \mathbf{H}^2) holds, then there exist positive constants β, R_0, p such that*

$$\mu_\epsilon(\mathbb{R}^n \setminus B(0, r)) \leq e^{-\beta \frac{r^p}{\epsilon^2}}, \quad \epsilon \in (0, \epsilon_*),$$

for all $r \geq R_0$.

Proof. Let U be the uniform Lyapunov function of (2.1) for $\epsilon \in (0, \epsilon_*)$, according to \mathbf{H}^2). Since U is of class \mathcal{B}^* in \mathcal{N}_∞ , there is a function $H(\rho) \in L^1_{loc}([\rho_m, \infty))$, where ρ_m denotes the essential lower bound of U , such that

$$H(\rho) \geq |\nabla U(x)|^2, \quad x \in \Gamma_\rho(U)$$

and

$$\int_{\rho_m}^\rho \frac{1}{H(s)} ds \geq |x|^p, \quad x \in \Gamma_\rho(U)$$

for all $\rho > \rho_m$. Using positive definiteness of $A(x)$, we let $C_0 > 0$ be a constant such that

$$\epsilon^2 H(\rho) \geq C_0 \frac{1}{2} \epsilon^2 \sum_{i,j=1}^n a_{ij} \partial_i U(x) \partial_j U(x)$$

and denote $H_1(\rho) = \epsilon^2 H(\rho)/C_0$. It follows from Lemma 2.1 that

$$\mu_\epsilon(\mathbb{R}^n \setminus \Omega_\rho(U)) \leq e^{-\gamma \int_{\rho_m}^\rho \frac{1}{H_1(s)} ds} \leq e^{-\frac{\gamma C_0}{\epsilon^2} \int_{\rho_m}^\rho \frac{1}{H(s)} ds} \leq e^{-\frac{\gamma C_0}{\epsilon^2} |x|^p}$$

for each $x \in \Gamma_\rho(U)$ whenever $\rho > \rho_m$, where $\gamma > 0$ is the Lyapunov constant of U .

Let $R_0 = \max_{x \in \Gamma_{\rho_m}(U)} |x|$, and for each $r \geq R_0$, denote $\rho(r) = \min_{|y|=r} U(y)$. Let $r \geq R_0$ and take $x \in \Omega_{\rho(r)} \cap B(0, r)$. Then $\Omega_{\rho(r)} \subset B(0, r)$ and

$$\mu_\epsilon(\mathbb{R}^n \setminus B(0, r)) \leq \mu_\epsilon(\mathbb{R}^n \setminus \Omega_{\rho(r)}(U)) \leq e^{-\frac{\gamma C_0}{\epsilon^2} |x|^p} = e^{-\frac{\beta}{\epsilon^2} r^p},$$

where $\beta = \tau C_0$. □

Next, we estimate the concentration of stationary probability measures of (2.1) in the intermediate region \mathcal{N}_* to verify the first part of \mathbf{H}^1 . For any connected open set $S \subset \mathbb{R}^n$, we note that $\mu_\epsilon|_S =: \mu_\epsilon/\mu_\epsilon(S)$ is a stationary probability measure of (2.1) on S .

Lemma 3.1. *Assume \mathbf{H}^0 and let W be as in \mathbf{H}^0 and $\rho_0 > 0$ be such that $\Omega_{\rho_0}(W) \subset \mathcal{N}$ and $\Gamma_{\rho_0} \cap \mathcal{A} \neq \emptyset$. Then there is an $\epsilon_0 \in (0, \epsilon_*)$ such that*

$$\mu_\epsilon(\mathcal{N} \setminus \Omega_{\rho_0}(W)) \leq e^{-\frac{C_1}{\epsilon^2}}, \quad \epsilon \in (0, \epsilon_0),$$

where $C_1 > 0$ is a constant independent of ϵ .

Proof. It is easy to see that there exists an $\epsilon_0 \in (0, \epsilon_*)$ such that W becomes a uniform Lyapunov function of (2.1) for all $\epsilon \in (0, \epsilon_0)$ in $S =: \mathcal{N}$, with upper bound $\rho^0 = \sup\{\rho > 0 : \Omega_\rho(W) \subset \mathcal{N}\}$ and essential lower bound ρ_0 . The lemma now follows from an application of Lemma 2.1 to $\mu_\epsilon|_{\mathcal{N}}$ with

$$H(\rho) = \frac{1}{2} \epsilon^2 \min_{x \in \Gamma_\rho(W)} \left(\sum_{i,j=1}^n a_{ij}(x) \partial_{x_i} W(x) \partial_{x_j} W(x) \right), \quad \rho \in (\rho_0, \rho^0).$$

□

Proposition 3.2. *Assume \mathbf{H}^0 , \mathbf{H}^2 and let W be as in \mathbf{H}^0 and R_0 be as in Proposition 3.1. Then there are constants $\rho_0, c_0 > 0$ and $\epsilon_0 \in (0, \epsilon_*)$ such that*

$$\mu_\epsilon(B(0, R_0) \setminus \Omega_{\rho_0}(W)) \leq e^{-\frac{c_0}{\epsilon^2}}, \quad \epsilon \in (0, \epsilon_0).$$

Proof. Let $U, \rho_m, \bar{\rho}_m$ be as in \mathbf{H}^2) and $\bar{\rho}_M \in (\rho_m, \infty)$ be such that $B(0, R_0) \subset \Omega_{\bar{\rho}_M}(U)$. Without loss of generality, we assume that $\Gamma_{\bar{\rho}_m}(U) \cap \mathcal{A} = \emptyset$. Denote $\rho^0 = \sup\{\rho > 0 : \Omega_\rho(W) \subset \mathcal{N}\}$ and let $\rho_0 \in (0, \rho^0)$, $\bar{\rho}_* \in (\rho_0, \rho^0)$ be such that $\Gamma_{\bar{\rho}_0}(W) \cap \mathcal{A} = \emptyset$, $\Omega_{\rho_0}(W) \subset \Omega_{\bar{\rho}_m}(U) \subset \Omega_{\bar{\rho}_*}(U) \subset \Omega_{\rho^0}(W)$.

By Lemma 3.1, there exists an $\epsilon_0 > 0$ and a constant $C_1 > 0$ such that

$$(3.1) \quad \mu_\epsilon(\mathcal{N} \setminus \Omega_{\rho_0}(W)) \leq e^{-\frac{C_1}{\epsilon^2}}, \quad \epsilon \in (0, \epsilon_0).$$

Since U is a uniform Lyapunov function of (2.1) for $\epsilon \in (0, \epsilon_*)$ on $S =: \Omega_{\bar{\rho}_M}(U)$, an application of Lemma 2.2 to $\mu_\epsilon|_S$ with

$$\begin{aligned} H_1(\rho) &= \frac{1}{2}\epsilon^2 \min_{x \in \Gamma_\rho(U)} \left(\sum_{i,j=1}^n a_{ij}(x) \partial_i U(x) \partial_j U(x) \right), \\ H_2(\rho) &= \frac{1}{2}\epsilon^2 \max_{x \in \Gamma_\rho(U)} \left(\sum_{i,j=1}^n a_{ij}(x) \partial_i U(x) \partial_j U(x) \right), \quad \rho \in (\bar{\rho}_m, \bar{\rho}_M), \end{aligned}$$

yields that there is a constant $C_2 > 0$ independent of ϵ such that

$$(3.2) \quad \begin{aligned} \mu_\epsilon(B(0, R_0) \setminus \Omega_{\rho_0}(W)) &\leq \mu_\epsilon(S \setminus \Omega_{\bar{\rho}_m}(U)) + \mu_\epsilon(\mathcal{N} \setminus \Omega_{\rho_0}(W)) \\ &\leq C_2 \mu_\epsilon(\Omega_{\bar{\rho}_*}(U) \setminus \Omega_{\bar{\rho}_m}(U)) + \mu_\epsilon(\mathcal{N} \setminus \Omega_{\rho_0}(W)) \\ &\leq (C_2 + 1) \mu_\epsilon(\mathcal{N} \setminus \Omega_{\rho_0}(W)). \end{aligned}$$

The proposition now easily follows from (3.1), (3.2). □

Now, Propositions 3.1, 3.2 immediately yields the following result.

Corollary 3.1. *Conditions \mathbf{H}^0 , \mathbf{H}^2 imply \mathbf{H}^1 .*

Below, we give a simple example that satisfies \mathbf{H}^0) and \mathbf{H}^2).

Example 3.1. *Consider*

$$(3.3) \quad \begin{cases} x' = y + x(1 - x^2 - y^2) \\ y' = -x + y(1 - x^2 - y^2). \end{cases}$$

Let

$$U(x, y) = \sqrt{x^2 + y^2} h(\sqrt{x^2 + y^2}) + (x^2 + y^2 - 1)^2 (1 - h(\sqrt{x^2 + y^2}))$$

where $h(r)$ is a nonnegative nondecreasing C^2 cut-off function such that $h(r) = 0$ for $r \leq 1.3$ and $h(r) = 1$ for $r \geq 1.4$. Then it is easy to verify that $U(x, y)$ is of class \mathcal{B}^* in $\{(x, y) : \sqrt{x^2 + y^2} \geq 1.4\}$. When ϵ is sufficiently small, the other conditions in \mathbf{H}^2) and \mathbf{H}^0) are also satisfied.

Remark 3.4. Example 3.1 is not a biological example. The purpose of having this simple example is to show that two Lyapunov functions can be “glued” to verify \mathbf{H}^2). In applications, if an ODE system has inward-pointing vector field far away from the origin, it is usually easy to find a Lyapunov function of class \mathcal{B}^* in \mathcal{N}_∞ . This Lyapunov function in \mathcal{N}_∞ may not have the Lyapunov property near the attractor. On the other hand, many ODE systems in biological models, such as mass-action systems, admit natural Lyapunov functions [15, 16, 19, 23], which are not of class \mathcal{B}^* in \mathcal{N}_∞ . Often two Lyapunov functions can be “glued” together to satisfy \mathbf{H}^2), which, by Corollary 3.1, rigorously leads to the desired concentration of μ_ϵ needed in the rest of this paper. We remind readers that there are some systematic ways to propagate “local” Lyapunov functions to construct a global Lyapunov function [2, 21], which can be used to check the validity of \mathbf{H}^2) in applications.

3.2. Concentration of stationary measures near the global attractor. Let L_1 be as in \mathbf{H}^0) and denote γ_0 as the Lyapunov constant of W . The following lemma is straightforward from the C^2 smoothness of W .

Lemma 3.2. *Assume \mathbf{H}^0). Then there are positive constants $\kappa, L_1, L_2, K_1, K_2$ such that*

$$\begin{aligned} -\kappa|\nabla W(x)|^2 &\leq \nabla W(x) \cdot f(x) \leq -\gamma_0|\nabla W(x)|^2, \\ L_1\text{dist}^2(x, \mathcal{A}) &\leq W(x) \leq L_2\text{dist}^2(x, \mathcal{A}), \\ K_1\text{dist}(x, \mathcal{A}) &\leq |\nabla W(x)| \leq K_2\text{dist}(x, \mathcal{A}), \end{aligned}$$

$x \in \mathcal{N}$.

Below, for any bounded set $A \subset \mathbb{R}^n$ and $r > 0$, we denote $B(A, r) := \{x \in \mathbb{R}^n : \text{dist}(x, A) \leq r\}$ as the r -neighborhood of A . The following theorems give new estimations in the vicinity of \mathcal{A} .

Theorem 3.2. *If both \mathbf{H}^0) and \mathbf{H}^1) hold, then for any $0 < \delta \ll 1$ there exist constants $\epsilon_0, M > 0$ such that*

$$\mu_\epsilon(B(\mathcal{A}, M\epsilon)) \geq 1 - \delta,$$

whenever $\epsilon \in (0, \epsilon_0)$.

Proof. Fix a $\rho_0 > 0$ such that $\Omega_{\rho_0}(W) \subset \mathcal{N}$ and $\Gamma_{\rho_0} \cap \mathcal{A} = \emptyset$. Then by Lemma 3.1 there are constants $\epsilon_0, C_1 > 0$ such that $\mu_\epsilon(\mathcal{N} \setminus \Omega_{\rho_0}(W)) < e^{-C_1/\epsilon^2}$, $\epsilon \in (0, \epsilon_0)$. Since by \mathbf{H}^1), $\mu_\epsilon(\mathbb{R}^n \setminus \mathcal{N}) = o(\epsilon^2)$, $0 < \epsilon \ll 1$, we only need to estimate $\mu_\epsilon(\Omega_{\rho_0}(W))$.

For any given $0 < \tilde{\rho}_0 < \rho_0$ and any $0 < \Delta\rho \ll 1$, consider the following C^2 cut-off function

$$\phi(\rho) = \begin{cases} 0, & \rho \leq \tilde{\rho}_0 \\ \frac{3}{\Delta\rho^4}(\rho - \tilde{\rho}_0)^5 - \frac{8}{\Delta\rho^3}(\rho - \tilde{\rho}_0)^4 + \frac{6}{\Delta\rho^2}(\rho - \tilde{\rho}_0)^3, & \tilde{\rho}_0 < \rho < \tilde{\rho}_0 + \Delta\rho \\ \rho - \tilde{\rho}_0, & \rho \geq \tilde{\rho}_0 + \Delta\rho. \end{cases}$$

Let $u = u_\epsilon$ be a density function of μ_ϵ . It follows from Theorem 2.2 that

$$(3.4) \quad \int_{\Omega_{\rho_0}(W)} \phi'(W(x)) \left(\sum_{i,j=1}^n \frac{1}{2} \epsilon^2 a_{ij}(x) \partial_{ij}^2 W(x) + \sum_{i=1}^n f_i(x) \partial_i W(x) \right) u(x) dx$$

$$+ \int_{\Omega_{\rho_0}(W)} \phi''(W(x)) \left(\sum_{i,j=1}^n \frac{1}{2} \epsilon^2 a_{ij}(x) \partial_i W(x) \partial_j W(x) \right) u(x) dx$$

$$(3.5) \quad = \int_{\Gamma_{\rho_0}(W)} \left(\sum_{i=1}^n \sum_{j=1}^n \frac{1}{2} \epsilon^2 a_{ij}(x) \partial_i W(x) \nu_j(x) \right) u(x) dx \geq 0,$$

where $\nu_j = \frac{\partial W_j}{|\nabla W|}$ for each j .

To estimate the first term on the left hand side of (3.5), we note by definition of $\phi(\rho)$ that

$$\int_{\Omega_{\rho_0}(W)} \phi'(W(x)) \left(\sum_{i,j=1}^n \frac{1}{2} \epsilon^2 a_{ij}(x) \partial_{ij}^2 W(x) + \sum_{i=1}^n f_i(x) \partial_i W(x) \right) u(x) dx$$

$$= \int_{\Omega_{\rho_0}(W) \setminus \Omega_{\tilde{\rho}_0}(W)} \phi'(W(x)) \left(\sum_{i,j=1}^n \frac{1}{2} \epsilon^2 a_{ij}(x) \partial_{ij}^2 W(x) + \sum_{i=1}^n f_i(x) \partial_i W(x) \right) u(x) dx.$$

Denote

$$\begin{aligned}\bar{\sigma} &= n^2 \max_{1 \leq i, j \leq n, x \in U_{\rho_0}(W)} |a_{ij}(x)|, \\ D &= \max_{1 \leq i, j \leq n, x \in U_{\rho_0}(W)} \partial_{ij}^2 W(x)\end{aligned}$$

and let $M_1 = D\bar{\sigma}/\gamma_0 K_1^2$, where γ_0 and K_1 are constants in Lemma 3.2. Let $\epsilon_1 > 0$ be such that $B(\mathcal{A}, \sqrt{M_1}\epsilon) \subset \Omega_{\rho_0}(W)$ for all $0 < \epsilon < \epsilon_1$. Then

$$\sum_{i,j=1}^n \frac{1}{2} \epsilon^2 a_{ij}(x) \partial_{ij}^2 W(x) \leq \frac{\gamma_0}{2} |\nabla W(x)|^2,$$

for all x with $\text{dist}(x, \mathcal{A}) > \sqrt{M_1}\epsilon$ and $\epsilon \in (0, \epsilon_1)$. It follows from the property of strong Lyapunov function that

$$\sum_{i,j=1}^n \frac{1}{2} \epsilon^2 a_{ij}(x) \partial_{ij}^2 W(x) + \sum_{i=1}^n f_i(x) \partial_i W(x) \leq -\frac{1}{2} \gamma_0 |\nabla W(x)|^2$$

for all x with $\text{dist}(x, \mathcal{A}) > \sqrt{M_1}\epsilon$ and $\epsilon \in (0, \epsilon_1)$. Let $\mathcal{D}_0 = \Omega_{\rho_0}(W) \setminus \Omega_{\tilde{\rho}_0 + \Delta\rho}$ and $\mathcal{D} = \Omega_{\tilde{\rho}_0 + \Delta\rho}(W) \setminus \Omega_{\tilde{\rho}_0}$. By Lemma 3.2, we also have

$$\begin{aligned}\min_{\mathcal{D}_0} |\nabla W(x)|^2 &\geq K_1^2 \min_{\mathcal{D}_0} \text{dist}^2(x, \mathcal{A}) \geq \frac{K_1^2}{L_2} \min_{\mathcal{D}_0} W(x) = \frac{K_1^2}{L_2} (\tilde{\rho}_0 + \Delta\rho) \\ &\geq \frac{K_1^2}{L_2} \max_{\mathcal{D}} W(x) \geq \frac{K_1^2 L_1}{L_2} \max_{\mathcal{D}} \text{dist}^2(x, \mathcal{A}) \\ &\geq \frac{K_1^2 L_1}{K_2^2 L_2} \max_{\mathcal{D}} |\nabla W(x)|^2 =: C_1 \max_{\mathcal{D}} |\nabla W(x)|^2,\end{aligned}$$

where K_1, K_2, L_1, L_2 are as in Lemma 3.2. Therefore,

$$\begin{aligned}&\int_{\Omega_{\rho_0}(W) \setminus \Omega_{\tilde{\rho}_0}(W)} \phi'(W(x)) \left(\sum_{i,j=1}^n \frac{1}{2} \epsilon^2 a_{ij}(x) \partial_{ij}^2 W(x) + \sum_{i=1}^n f_i(x) \partial_i W(x) \right) u(x) dx \\ &\leq -\gamma_0 \int_{\Omega_{\rho_0}(W) \setminus \Omega_{\tilde{\rho}_0}(W)} \phi'(W(x)) |\nabla W(x)|^2 u(x) dx \leq -\gamma_0 \int_{\Omega_{\rho_0}(W) \setminus \Omega_{\tilde{\rho}_0 + \Delta\rho}(W)} |\nabla W(x)|^2 u(x) dx \\ &\leq -\gamma_0 \min_{\mathcal{D}_0} |\nabla W(x)|^2 \int_{\Omega_{\rho_0}(W) \setminus \Omega_{\tilde{\rho}_0 + \Delta\rho}(W)} u(x) dx \\ (3.6) &\leq -\gamma_0 C_1 \max_{\mathcal{D}} |\nabla W(x)|^2 \mu_\epsilon(\Omega_{\rho_0}(W) \setminus \Omega_{\tilde{\rho}_0 + \Delta\rho}(W)).\end{aligned}$$

Note that $|\phi''(x)| \leq 4$. The second term on the left hand side of (3.5) simply satisfies the following estimate:

$$\begin{aligned}&\int_{\Omega_{\rho_0}(W)} \phi''(W(x)) \sum_{i,j=1}^n \frac{1}{2} \epsilon^2 a_{ij}(x) \partial_i W(x) \partial_j W(x) u dx \\ &= \int_{\Omega_{\tilde{\rho}_0 + \Delta\rho}(W) \setminus \Omega_{\tilde{\rho}_0}(W)} \phi''(W(x)) \sum_{i,j=1}^n \frac{1}{2} \epsilon^2 a_{ij}(x) \partial_i W(x) \partial_j W(x) u dx \\ (3.7) &\leq \frac{2}{\Delta\rho} \epsilon^2 \bar{\lambda} \max_{\mathcal{D}} |\nabla W(x)|^2 \mu_\epsilon(\Omega_{\tilde{\rho}_0 + \Delta\rho} \setminus \Omega_{\tilde{\rho}_0}),\end{aligned}$$

where $\bar{\lambda} = \sup_{x \in \Omega_{\rho_0}(W)} \lambda_M(x)$ with $\lambda_M(x)$ being the largest eigenvalue of matrix $A(x)$ for each $x \in \Omega_{\rho_0}(W)$.

It now follows from (3.5)-(3.7) that

$$(3.8) \quad -\gamma_0 C_1 \mu(\Omega_{\rho_0}(W) \setminus \Omega_{\tilde{\rho}_0 + \Delta\rho}(W)) + \frac{2}{\Delta\rho} \epsilon^2 \bar{\lambda} \mu(\Omega_{\tilde{\rho}_0 + \Delta\rho}(W) \setminus \Omega_{\tilde{\rho}_0}(W)) \geq 0.$$

Let $\rho_1 = L_2 M_1 \epsilon^2$. We have by Lemma 3.2 that $B(\mathcal{A}, \sqrt{M_1} \epsilon) \subset \Omega_{\rho_1}$. Consider function $F(\rho) = \mu_\epsilon(\Omega_{\rho_0}(W) \setminus \Omega_\rho(W))$, $\rho \in [\rho_1, \rho_0]$. Since $\tilde{\rho}_0$ is arbitrary, (3.8) with ρ in place of $\tilde{\rho}_0$ becomes

$$-\gamma_0 C_1 F(\rho + \Delta\rho) + \frac{2}{\Delta\rho} \epsilon^2 \bar{\lambda} (F(\rho) - F(\rho + \Delta\rho)) \geq 0, \quad \rho \in [\rho_1, \rho_0].$$

Taking limit $\Delta\rho \rightarrow 0$ in the above yields

$$\gamma_0 C_1 F(\rho) + 2\epsilon^2 \bar{\lambda} F'(\rho) \leq 0.$$

Hence, by Gronwall's inequality, we have

$$(3.9) \quad F(\rho) \leq F(\rho_1) e^{-\frac{\gamma_0 C_1}{2\epsilon^2 \bar{\lambda}} (\rho - \rho_1)}, \quad \rho \in [\rho_1, \rho_0].$$

For a given sufficiently small $\delta > 0$, we let

$$M_2 = L_2 M_1 - \frac{2\bar{\lambda}}{\gamma_0} C_1 \log \frac{\delta}{2}.$$

Then it is easy to see from (3.9) that

$$(3.10) \quad F(M_2 \epsilon^2) = \mu_\epsilon(\Omega_{\rho_0}(W)) - \mu_\epsilon(\Omega_{M_2 \epsilon^2}(W)) \leq \frac{\delta}{2},$$

whenever $\epsilon < \epsilon_2 =: \frac{\rho_0}{M_2}$.

Since $\mu_\epsilon(\mathbb{R}^n \setminus \Omega_{\rho_0}(W)) < e^{-C_0/\epsilon^2} + o(\epsilon^2)$, there exists an $\epsilon_3 > 0$ such that $\mu_\epsilon(\mathbb{R}^n \setminus \Omega_{\rho_0}(W)) < \frac{\delta}{2}$, i.e., $\mu_\epsilon(\Omega_{\rho_0}(W)) > 1 - \frac{\delta}{2}$, for all $\epsilon \in (0, \epsilon_3)$. Hence by (3.10),

$$\mu_\epsilon(\Omega_{M_2 \epsilon^3}(W)) \geq 1 - \delta, \quad 0 < \epsilon < \epsilon_0,$$

where $\epsilon_0 = \min\{\epsilon_1, \epsilon_2, \epsilon_3\}$.

Let $M = \sqrt{\frac{M_2}{L_1}}$. Then by Lemma 3.2,

$$\Omega_{M_2 \epsilon^2}(W) \subset B(\mathcal{A}, M\epsilon),$$

and therefore,

$$\mu_\epsilon(B(\mathcal{A}, M\epsilon)) \geq \mu_\epsilon(\Omega_{M_2 \epsilon^2}(W)) \geq 1 - \delta, \quad 0 < \epsilon < \epsilon_0.$$

This completes the proof. \square

Remark 3.5. 1) From the proof of Theorem 3.2, one sees that the constant M grows in a logarithm rate as δ decreases. In fact, for a fixed small ϵ , we have

$$\lim_{\delta \rightarrow 0} \frac{M}{\sqrt{-\log \delta}} = C$$

for some finite constant C .

2) Theorem 3.2 does not follow from Lemma 2.1 directly simply because for any constant $M > 0$ the Lyapunov constant of W in the set $\Omega_{M\epsilon^2}(W)$ becomes $O(\epsilon)$ instead of being $O(1)$.

Next we estimate the lower bound of concentration of μ_ϵ .

Lemma 3.3. *There is a constant $r_0 > 0$ such that $\sum_{i,j=1}^n a_{ij}(x) W_{ij}(x)$ is uniformly positive in $B(\mathcal{A}, r_0)$.*

Proof. First we note that the Hessian matrix $\mathbf{H}(x) := (W_{ij}(x))$ of $W(x)$ must be positive semidefinite for all $x \in \mathcal{A}$. For otherwise, there is $x_0 \in \mathcal{A}$ such that $\mathbf{H}(x_0)$ has negative eigenvalue. It then follows from the C^2 smoothness of $W(x)$ that $W(x)$ must take a negative value at some $x \in \mathcal{N}$ where $x - x_0$ is an eigenvector corresponding to the negative eigenvalue of $\mathbf{H}(x_0)$. This is a contradiction because $W(x)$ must be everywhere non-negative in \mathcal{N} .

Since $A(x) = (a_{ij}(x))$ is everywhere positive definite in $\bar{\mathcal{N}}$, all its eigenvalues in \mathcal{N} are bounded below by a positive constant λ_0 . For any $x_0 \in \mathcal{A}$, since $W(x) \geq L_1 \text{dist}(x, \mathcal{A})^2$, $x \in \mathcal{N}$, Taylor expansion of W at x_0 shows that at least one eigenvalue of $\mathbf{H}(x_0)$ must be positive. Consequently,

$$\sum_{i,j=1}^n a_{ij}(x_0)W_{ij}(x_0) = \text{trace}(A(x_0)\mathbf{H}(x_0)) \geq \lambda_0 \text{trace}(\mathbf{H}(x_0)) > 0.$$

The proposition simply follows from the continuity of $\sum_{i,j=1}^n a_{ij}(x)W_{ij}(x)$. □

Theorem 3.3. *If both \mathbf{H}^0 and \mathbf{H}^1 hold, then*

$$\lim_{\epsilon \rightarrow 0} \mu_\epsilon(\{x : \epsilon^{1+\alpha} \leq \text{dist}(x, \mathcal{A}) \leq \epsilon^{1-\alpha}\}) = 1$$

for any $0 < \alpha < 1$.

Proof. By Lemma 3.2, there is a constant $\epsilon_0 > 0$ such that both $\{x | \text{dist}(x, \mathcal{A}) \leq \epsilon^{1-\alpha}\} \subseteq \Omega_{\epsilon^{2-\alpha}}(W)$ and $\{x | \text{dist}(x, \mathcal{A}) \leq \epsilon^{1+\alpha}\} \supseteq \Omega_{\epsilon^{2+3\alpha}}(W)$ hold for all $\epsilon \in (0, \epsilon_0)$. Thus it suffices to prove that

$$(3.11) \quad \lim_{\epsilon \rightarrow 0} \mu_\epsilon(\Omega_{\epsilon^{2+\delta}}(W)) = 0,$$

$$(3.12) \quad \lim_{\epsilon \rightarrow 0} \mu_\epsilon(\Omega_{\epsilon^{2-\delta}}(W)) = 1.$$

for any fixed $\delta > 0$.

Equation (3.12) follows from Theorem 3.2 immediately. We will prove equation (3.11).

Fix a $\rho_0 > 0$ such that $\Omega_{\rho_0}(W) \subseteq \mathcal{N}$ and $\Gamma_{\rho_0} \cap \mathcal{A} = \emptyset$. Consider $f(\rho) = \mu_\epsilon(\Omega_\rho(W))$ for $\rho \in [0, \rho_0]$. Assume, for the sake of contradiction, that there is a constant $\sigma > 0$ such that $f(\epsilon^{2+\delta}) \geq \sigma > 0$ for any sufficient small $\epsilon > 0$.

We have by Theorem 2.3 that

$$(3.13) \quad \int_{\Gamma_\rho(W)} \frac{u(x)}{|\nabla W(x)|} ds = f'(\rho).$$

Let $\bar{\lambda} = \sup_{x \in \Omega_{\rho_0}(W)} \lambda_M(x)$ with $\lambda(x)$ being the largest eigenvalue of matrix $A(x)$ for each $x \in \Omega_{\rho_0}(W)$. Let $u = u_\epsilon$ be the density function of μ_ϵ . It follows from Lemma 3.2 and (3.13) that for each $0 < \rho < \rho_0$, inequality

$$\begin{aligned} \int_{\Gamma_\rho(W)} \frac{1}{2} \epsilon^2 \left(\sum_{i,j=1}^n a_{ij}(x) \partial_i W(x) \nu_j(x) \right) u(x) ds &= \int_{\Gamma_\rho(W)} \frac{1}{2} \epsilon^2 \left(\sum_{i,j=1}^n a_{ij}(x) \partial_i W(x) \partial_j W(x) \right) \frac{u(x)}{|\nabla W(x)|} ds \\ &\leq \int_{\Gamma_\rho(W)} \frac{1}{2} \epsilon^2 \bar{\lambda} |\nabla W(x)|^2 \frac{u(x)}{|\nabla W(x)|} ds \\ &\leq \int_{\Gamma_\rho(W)} \frac{1}{2} \epsilon^2 \bar{\lambda} \frac{K_2^2}{L_1} W(x) \frac{u(x)}{|\nabla W(x)|} ds \\ &\leq \epsilon^2 C_1 \rho f'(\rho) \end{aligned}$$

holds for some positive constant $C_1 < \infty$.

By Lemma 3.2, we have the inequality

$$(3.14) \quad \sum_{i=1}^n f_i(x) \partial_i W(x) \geq -\kappa |\nabla W(x)|^2 \geq -\kappa \frac{K_2^2}{L_1} W(x).$$

It then follows from Lemma 3.3 and (3.14) that there are positive constants p, C_2 and ϵ_0 such that

$$\frac{1}{2} \epsilon^2 \sum_{i,j=1}^n a_{ij}(x) W_{ij}(x) + \sum_{i=1}^n f_i(x) \partial_i W(x) \geq p \epsilon^2$$

for all $x \in \Omega_{C_2 \epsilon^2}(W)$ and $\epsilon \in (0, \epsilon_0)$. Without loss of generality, we make ϵ sufficiently small such that $\rho_0 > C_2 \epsilon^2$. Then for each $\rho \leq C_2 \epsilon^2$ there holds

$$\int_{\Omega_\rho(W)} \left(\frac{1}{2} \epsilon^2 \sum_{i,j=1}^n a_{ij}(x) W_{ij}(x) + \sum_{i=1}^n f_i(x) \partial_i W(x) \right) u dx \geq p f(\rho) \epsilon^2.$$

Since by Theorem 2.2,

$$\int_{\Omega_\rho(W)} \left(\frac{1}{2} \epsilon^2 \sum_{i,j=1}^n a_{ij}(x) W_{ij}(x) + \sum_{i=1}^n f_i(x) \partial_i W(x) \right) u dx = \int_{\Gamma_\rho(W)} \frac{1}{2} \epsilon^2 \left(\sum_{i,j=1}^n a_{ij}(x) \partial_i W(x) \nu_j(x) \right) u(x) ds.$$

we conclude that

$$p f(\rho) \epsilon^2 \leq \epsilon^2 C_1 \rho f'(\rho)$$

for each $0 < \rho \leq C_2 \epsilon^2$. Thus

$$(3.15) \quad \frac{f'(\rho)}{f(\rho)} \geq \frac{p}{C_1 \rho}.$$

Integrating (3.15) from $\epsilon^{2+\delta}$ to $C_2 \epsilon^2$ yields

$$\log f(C_2 \epsilon^2) - \log \sigma \geq \frac{p}{C_1} (\log C_2 - \delta \log \epsilon).$$

As $\epsilon \rightarrow 0$, we have $f(C_2 \epsilon^2) \rightarrow \infty$. This contradicts to the fact that $f(\rho) \leq 1$. Hence $f(\epsilon^{2+\delta}) = \mu_\epsilon(\Omega_{\epsilon^{2+\delta}}) \rightarrow 0$. This completes the proof. \square

Remark 3.6. Theorem 3.3 says that the density function of μ_ϵ cannot be “too narrow” because almost all the mass of μ_ϵ is located in the set $\{x : \epsilon^{1+\alpha} \leq \text{dist}(x, \mathcal{A}) \leq \epsilon^{1-\alpha}\}$.

3.3. Mean square displacement. The concentration of μ_ϵ can be more concretely measured by the *mean square displacement* defined by

$$V(\epsilon) = \int_{\mathbb{R}^n} \text{dist}^2(x, \mathcal{A}) d\mu_\epsilon.$$

The following theorem gives bounds of the mean square displacement.

Theorem 3.4. *If both \mathbf{H}^0) and \mathbf{H}^*) hold, then there are constants $V_1, V_2, \epsilon_0 > 0$ independent of ϵ such that*

$$V_2 \epsilon^2 \leq V(\epsilon) \leq V_1 \epsilon^2, \quad \epsilon \in (0, \epsilon_0).$$

Proof. Fix a $\rho_0 > 0$ such that $\Omega_{\rho_0}(W) \subset \mathcal{N}$ and $\Gamma_{\rho_0}(W) \cap \mathcal{A} = \emptyset$. We have by condition **H¹**) and Lemma 3.1 that there is an $\epsilon_0 \in (0, \epsilon^*)$ sufficiently small such that

$$(3.16) \quad \mu_\epsilon(\mathbb{R}^n \setminus \Omega_{\rho_0}(W)) < \epsilon^2, \quad \epsilon \in (0, \epsilon_0).$$

Consider the function

$$G(\rho) = \int_{\Omega_{\rho_0} \setminus \Omega_\rho} |\nabla W(x)|^2 d\mu_\epsilon, \quad \rho \in [0, \rho_0].$$

Then it follows from Lemma 3.2 that

$$\begin{aligned} \frac{1}{K_2^2} G(0) &\leq \int_{\Omega_{\rho_0}(W)} \text{dist}^2(x, \mathcal{A}) d\mu_\epsilon \leq V(\epsilon) \\ &= \int_{\Omega_{\rho_0}(W)} \text{dist}^2(x, \mathcal{A}) d\mu_\epsilon + \int_{\mathbb{R}^n \setminus \Omega_{\rho_0}(W)} \text{dist}^2(x, \mathcal{A}) d\mu_\epsilon \\ &\leq \frac{1}{K_1^2} G(0) + \int_{\mathbb{R}^n \setminus \Omega_{\rho_0}(W)} \text{dist}^2(x, \mathcal{A}) d\mu_\epsilon, \end{aligned}$$

where K_1, K_2 are as in Lemma 3.2.

We first estimate an upper bound of $G(0)$ in term of ϵ^2 . Let $F(\rho) = \mu_\epsilon(\Omega_{\rho_0}(W) \setminus \Omega_\rho(W))$. Then it follows from equation (3.9) that

$$(3.17) \quad F(\rho) \leq F(\rho_1) e^{-\frac{2\gamma_0 C_1}{\epsilon^2 \bar{\lambda}}(\rho - \rho_1)} \leq e^{-\frac{2\gamma_0 C_1}{\epsilon^2 \bar{\lambda}}(\rho - \rho_1)}, \quad \rho \in (\rho_1, \rho_0),$$

for all $0 < \epsilon \ll 1$, where $C_1, \bar{\lambda}, \gamma_0$ are constants independent of ϵ and $\rho_1 = C_2 \epsilon^2$ for some constant C_2 independent of ϵ . Since by Lemma 3.2, $|\nabla W|^2 \leq K_2^2 \rho / L_1$, we have by (3.17) and Theorem 2.3 that

$$\begin{aligned} &\int_{\Omega_{\rho_0}(W) \setminus \Omega_{\rho_1}(W)} |\nabla W(x)|^2 d\mu_\epsilon \leq - \int_{\rho_1}^{\rho_0} \frac{K_2^2}{L_1} \rho F'(\rho) d\rho \\ &= - \frac{K_2^2}{L_1} \rho F(\rho) \Big|_{\rho_1}^{\rho_0} + \frac{K_2^2}{L_1} \int_{\rho_1}^{\rho_0} F(\rho) d\rho \\ &\leq \frac{K_2^2}{L_1} \rho_1 F(\rho_1) + \frac{K_2^2}{L_1} \int_{\rho_1}^{\infty} e^{-\frac{2\gamma_0 C_1}{\epsilon^2 \bar{\lambda}} s} ds \leq \frac{K_2^2}{L_1} (C_2 \epsilon^2 + \frac{\bar{\lambda} \epsilon^2}{2\gamma_0 C_1} e^{-\frac{2\gamma_0 C_1 \rho_1}{\epsilon^2 \bar{\lambda}}}) := E_2 \epsilon^2 \end{aligned}$$

for all $0 < \epsilon \ll 1$. By a simple calculation, we also have

$$\int_{\Omega_{\rho_1}(W)} |\nabla W(x)|^2 d\mu_\epsilon \leq M_2 \epsilon^2$$

as $0 < \epsilon \ll 1$, where $M_2 > 0$ is a constant independent of ϵ . Thus,

$$(3.18) \quad \begin{aligned} G(0) &= \int_{\Omega_{\rho_0}(W)} |\nabla W(x)|^2 d\mu_\epsilon = \int_{\Omega_{\rho_0}(W) \setminus \Omega_{\rho_1}(W)} |\nabla W(x)|^2 d\mu_\epsilon + \int_{\Omega_{\rho_1}(W)} |\nabla W(x)|^2 d\mu_\epsilon \\ &\leq (E_2 + M_2) \epsilon^2, \quad 0 < \epsilon \ll 1. \end{aligned}$$

Next, we estimate an upper bound of $\int_{\mathbb{R}^n \setminus \Omega_{\rho_0}(W)} \text{dist}^2(x, \mathcal{A}) d\mu_\epsilon$. Let $R_0 > 0$ be as in **H¹**), i.e.,

$$\mu_\epsilon(\mathbb{R}^n \setminus B(0, r)) \leq e^{-\frac{r^p}{\epsilon^2}}, \quad r \geq R_0,$$

for all $\epsilon \in (0, \epsilon_*)$. Without loss of generality, we may assume that R_0 is sufficiently large such that

$$\text{dist}(x, \mathcal{A}) < 2|x|, \quad |x| \geq R_0.$$

Then

$$\begin{aligned} \int_{\mathbb{R}^n \setminus B(0, R_0)} \text{dist}^2(x, \mathcal{A}) d\mu_\epsilon &\leq \int_{\{|x| > R_0\}} 4|x|^2 u dx \leq 4 \sum_{k=k_0}^{\infty} e^{-\frac{k^p}{\epsilon^2}} (k+1)^{n+2} C(n) \\ &\leq 4e^{-\frac{k_0^p}{\epsilon^2}} \sum_{k=0}^{\infty} e^{-\frac{k^p}{\epsilon_0^2}} (k+k_0+1)^{n+2} C(n) \leq C_5 e^{-\frac{k_0^p}{\epsilon^2}} \end{aligned}$$

for all $\epsilon \in (0, \epsilon_*)$, where $C(n)$ is the volume of the unit sphere in \mathbb{R}^n , k_0 is the largest integer smaller than R_0 , and C_5 is a constant independent of ϵ . Thus, we can make ϵ_0 sufficiently small such that

$$(3.19) \quad \int_{\mathbb{R}^n \setminus B(0, R_0)} \text{dist}^2(x, \mathcal{A}) d\mu_\epsilon < \epsilon^2, \quad \epsilon \in (0, \epsilon_0).$$

Using (3.16), we can make ϵ_0 further small if necessary such that

$$(3.20) \quad \int_{B(0, R_0) \setminus \Omega_{\rho_0}(W)} \text{dist}^2(x, \mathcal{A}) d\mu_\epsilon < \epsilon^2, \quad \epsilon \in (0, \epsilon_0).$$

It now follows from (3.19) and (3.20) that

$$\begin{aligned} &\int_{\mathbb{R}^n \setminus \Omega_{\rho_0}(W)} \text{dist}^2(x, \mathcal{A}) d\mu_\epsilon \\ &= \int_{\mathbb{R}^n \setminus B(0, R_0)} \text{dist}^2(x, \mathcal{A}) d\mu_\epsilon + \int_{B(0, R_0) \setminus \Omega_{\rho_0}(W)} \text{dist}^2(x, \mathcal{A}) d\mu_\epsilon < 2\epsilon^2 \end{aligned}$$

for all $\epsilon \in (0, \epsilon_0)$. This, when combining with (3.18), yields that

$$V(\epsilon) \leq \left(2 + \frac{E_2}{K_1^2}\right) \epsilon^2 := V_1 \epsilon^2, \quad 0 < \epsilon \ll 1.$$

Finally, we estimate a lower bound of $V(\epsilon)$. For each $\epsilon \in (0, \epsilon^*)$, let $u = u_\epsilon$ be a density function of μ_ϵ . Then by Theorem 2.2

$$\begin{aligned} (3.21) \quad &\int_{\Omega_\rho(W)} \left(\frac{1}{2} \epsilon^2 \sum_{i,j=1}^n a_{ij}(x) W_{ij}(x) + \sum_{i=1}^n f_i(x) \partial_i W(x) \right) u(x) dx \\ &= \int_{\Gamma_\rho(W)} \frac{1}{2} \epsilon^2 \left(\sum_{i,j=1}^n a_{ij}(x) \partial_i W(x) \nu_j(x) \right) u(x) ds, \quad \rho \in (0, \rho_0). \end{aligned}$$

Let r_0 be as in Lemma 3.3 and fix a $\rho_* \in (0, \rho_0)$ such that $\Omega_{\rho_*}(W) \subset B(\mathcal{A}, r_0)$. Since $F(\rho_0) = 0$, we have by (3.17) and mean value theorem that there is a $\rho^* \in (\rho_*, \rho_0)$ such that $F'(\rho^*) \leq e^{-\frac{\beta}{\epsilon^2}} (\rho_0 - \rho_*)^{-1}$ as $0 < \epsilon < \epsilon_0$, where $\beta = \frac{2\gamma_0 C_1}{\lambda} (\rho_* - \rho_1)$. By \mathbf{H}^1) and Lemma 3.1, we can make ϵ_0 further small if necessary such that $\mu_\epsilon(\Omega_{\rho_*}(W)) \geq 1 - o(\epsilon^2)$ as $\epsilon \in (0, \epsilon_0)$. It follows from Lemma 3.3 that

$$(3.22) \quad \int_{\Omega_{\rho^*}(W)} \frac{1}{2} \epsilon^2 \sum_{i,j=1}^n a_{ij}(x) W_{ij}(x) u(x) dx \geq \int_{\Omega_{\rho^*}(W)} \frac{1}{2} \epsilon^2 \sum_{i,j=1}^n a_{ij}(x) W_{ij}(x) u(x) dx \geq C_4 \epsilon^2$$

as $0 < \epsilon < \epsilon_0$, where $C_4 > 0$ is a constant independent of ϵ . By Lemma 3.2, we also have

$$(3.23) \quad \int_{\Omega_{\rho^*}(W)} \sum_{i=1}^n f_i(x) \partial_i W(x) u(x) dx \geq -\kappa \int_{\Omega_{\rho^*}(W)} |\nabla W(x)|^2 u(x) dx \geq -\kappa G(0).$$

Let $C_5 = \frac{1}{2} \sup_{x \in \mathcal{N}} \sum_{i,j=1}^n a_{ij} \partial_i W \partial_j W$ and assume without loss of generality that $C_5 e^{-\frac{\beta}{\epsilon^2}} (\rho_0 - \rho_*)^{-1} < C_4/2$, $\epsilon \in (0, \epsilon_0)$. It follows from Theorem 2.3 that

$$\begin{aligned}
 (3.24) \quad & \int_{\Gamma_{\rho^*}(W)} \frac{1}{2} \epsilon^2 \left(\sum_{i,j=1}^n a_{ij}(x) \partial_i W(x) \nu_j(x) \right) u(x) ds \\
 &= \int_{\Gamma_{\rho^*}(W)} \frac{1}{2} \epsilon^2 \left(\sum_{i,j=1}^n a_{ij}(x) \partial_i W(x) \partial_j W(x) \right) \frac{u(x)}{|\nabla W(x)|} ds \\
 &\leq \epsilon^2 C_5 \int_{\Gamma_{\rho^*}(W)} \frac{u(x)}{|\nabla W(x)|} ds = \epsilon^2 C_5 F'(\rho^*) \\
 (3.25) \quad &\leq \epsilon^2 C_5 e^{-\frac{\beta}{\epsilon^2}} (\rho_0 - \rho_*)^{-1} \leq \frac{C_4}{2} \epsilon^2,
 \end{aligned}$$

as $\epsilon \in (0, \epsilon_0)$. Now, (3.21)-(3.25) yield

$$G(0) \geq \frac{C_4}{2\kappa} \epsilon^2,$$

which implies

$$V(\epsilon) \geq \frac{C_4}{2\kappa K_2^2} \epsilon^2 := V_2 \epsilon^2$$

as $\epsilon \in (0, \epsilon_0)$. This completes the proof. \square

Remark 3.7. The mean square displacement is a natural extension of the variance. Consider $\mathcal{A}_1 = \{0\}$ and the Gaussian measure ν_ϵ with mean 0 and variance ϵ^2 . Then it is easy to see that Theorems 3.3, 3.4 hold for ν_ϵ and \mathcal{A}_1 . This is to say that, by assuming \mathbf{H}^0 and \mathbf{H}^1 , the concentration of μ_ϵ is Gaussian-like.

4. ENTROPY-DIMENSION RELATIONSHIP

In this section, we will investigate the connection between the differential entropy of stationary measures of (2.1) and the dimension of \mathcal{A} . This connection will be used in the second part of the series.

Let μ be a probability measure on \mathbb{R}^n with a density function $\xi(x)$. We recall that the relative entropy of μ with respect to Lebesgue measure, or the *differential entropy* of μ is defined as

$$(4.1) \quad \mathcal{H}(\mu) = - \int_{\mathbb{R}^n} \xi(x) \log \xi(x) dx.$$

4.1. Regularity of sets and measures. To establish the connection between the entropy of a stationary measure μ_ϵ of (2.1) and the dimension of \mathcal{A} , we will require \mathcal{A} be a regular set and μ_ϵ be a regular measure with respect to \mathcal{A} .

A set $A \subset \mathbb{R}^n$ is called a *regular set* if

$$\limsup_{r \rightarrow 0} \frac{\log m(B(A, r))}{\log r} = \liminf_{r \rightarrow 0} \frac{\log m(B(A, r))}{\log r} = n - d$$

for some $d \geq 0$, where $m(\cdot)$ denotes the Lebesgue measure on \mathbb{R}^n . It is easy to check that d is the Minkowski dimension of A . Regular sets form a large class that includes smooth manifolds and even fractal sets like Cantor sets. However, not all measurable sets are regular (see [37] for details).

Assume that (1.1) admits a global attractor \mathcal{A} and the Fokker-Planck equation (2.1) admits a stationary measure μ_ϵ for each $\epsilon \in (0, \epsilon_*)$. The family $\{\mu_\epsilon\}$ of stationary measures is said to be *regular*

with respect to \mathcal{A} if for any $\delta > 0$ there are constants K, C and a family of approximate functions $u_{K,\epsilon}$ supported on $B(\mathcal{A}, K\epsilon)$ such that for all $\epsilon \in (0, \epsilon^*)$,

a)

$$(4.2) \quad \inf_{B(\mathcal{A}, K\epsilon)} (u_{K,\epsilon}(x)) \geq C \sup_{B(\mathcal{A}, K\epsilon)} (u_{K,\epsilon}(x));$$

and

b)

$$\|u_\epsilon(x) - u_{K,\epsilon}(x)\|_{L^1} \leq \delta.$$

The following propositions give some examples of regular stationary measures.

Proposition 4.1. *Assume equation (1.2) has the form*

$$(4.3) \quad dX_t = -\nabla U(X)dt + \epsilon dW_t, \quad X \in \mathbb{R}^n,$$

where $U \in C^2(\mathbb{R}^n)$ is such that $U(x) \geq \beta \log|x|$ as $|x| \gg 1$ for some positive constant β . Then the family of stationary measures of the Fokker-Planck equations associated with (4.3) is regular with respect to \mathcal{A} as $0 < \epsilon \ll 1$.

Proof. For each $\epsilon \ll 1$, the Fokker-Planck equation associated with (4.3) admits a unique stationary measure μ_ϵ which actually coincides with the Gibbs measure with density

$$(4.4) \quad \frac{1}{K} e^{-\frac{U(x)}{\epsilon^2}},$$

where K is the normalizer (see e.g. [25] and references therein). The regularity of the family $\{\mu_\epsilon\}$ thus follows easily from (4.4) and the definition. \square

Proposition 4.2. *Consider (1.2) and assume that \mathbf{H}^1) holds. If \mathcal{A} is an equilibrium, then the family μ_ϵ is regular with respect to \mathcal{A} .*

Proof. Without loss of generality, we assume that $\mathcal{A} = \{0\}$. It follows from \mathbf{H}^1) and the WKB expansion (see [8, 9, 33]) that there is a function $W \in C^2(\mathbb{R}^n)$, called quasi-potential function, such that the density function of μ_ϵ for each $\epsilon \in (0, \epsilon^*)$ has the form

$$(4.5) \quad \frac{1}{K} z(x) e^{-\frac{W(x)}{\epsilon^2}} + o(\epsilon^2),$$

where K is the normalizer and $z \in C(\mathbb{R}^n)$. It is easy to see that $u_\epsilon(x)$ is regular. The regularity of the family $\{\mu_\epsilon\}$ then follows from (4.5) and the definition. \square

In many biological applications, WKB expansion as in (4.5) is assumed [6, 35, 36]. If the family of stationary measures satisfies (4.5), then it must be regular with respect to \mathcal{A} . However, if \mathcal{A} is not an equilibrium, verifying (4.5) is difficult in general. Still, although there are some technical huddles, proving that a stationary measure is regular with respect to the global attractor is possible in many cases.

If \mathcal{A} is a limit cycle on which f is everywhere non-vanishing, then equation (1.2) can be linearized in the vicinity of \mathcal{A} . The solution of the linearized equation can be explicitly given. Therefore the density function of μ_ϵ can be estimated via probabilistic approaches. We will prove in our future work that the family μ_ϵ is regular with respect to the limit cycle \mathcal{A} . In addition, we conjecture that when \mathbf{H}^1) holds for equation (1.2) and equation (1.1) admits an SRB measure, the family μ_ϵ is regular with respect to \mathcal{A} under suitable conditions.

4.2. Entropy and dimension. The main theorem of this subsection is the following entropy-dimension inequality.

Theorem 4.1. *Assume that \mathbf{H}^0) and \mathbf{H}^1) hold. If \mathcal{A} is a regular set, then*

$$(4.6) \quad \liminf_{\epsilon \rightarrow 0} \frac{\mathcal{H}(\mu_\epsilon)}{\log \epsilon} \geq n - d,$$

where d is the Minkowski dimension of \mathcal{A} .

To prove Theorem 4.1, the following three lemmas that estimate the integral of $u_\epsilon(x) \log u_\epsilon(x)$ are useful. The first lemma estimates the integral of $u_\epsilon(x) \log u_\epsilon(x)$ outside large spheres.

Lemma 4.1. *Let $l > 0$ be a fixed constant independent of ϵ . If \mathbf{H}^1) holds, then there exist positive constants ϵ_0, R_0 such that*

$$\int_{|x| > R_0} u_\epsilon(x) \log u_\epsilon(x) dx \geq -\epsilon^l,$$

for all $\epsilon \in (0, \epsilon_0)$.

Proof. It follows from \mathbf{H}^1) that μ_ϵ has the tail bounds

$$\mu_\epsilon(\mathbb{R}^n \setminus B(0, |x|)) = \int_{\mathbb{R}^n \setminus B(0, |x|)} u_\epsilon(x) dx \leq e^{-\frac{|x|^p}{\epsilon^2}}$$

for all $|x| > R_0$, where R_0 and p are positive constants independent of ϵ .

For each positive integer k , we denote $\Omega_k = \{x : k \leq |x| < k + 1\}$. Let k_0 be the smallest integer that is larger than R_* . Then for each $k > k_0$, we have

$$\int_{\Omega_k} u_\epsilon(x) dx \leq e^{-\frac{k^p}{\epsilon^2}}.$$

Let $\Omega_k = A_k \cup B_k$ where $A_k = \{x \in \Omega_k : u_\epsilon(x) \geq e^{-\frac{k^p}{\epsilon^2}}\}$, $B_k = \Omega_k \setminus A_k$. Since $x \log x$ decreases on the interval $(0, e^{-1})$, for sufficient small ϵ we have

$$\int_{A_k} u_\epsilon(x) \log u_\epsilon(x) dx \geq -\frac{k^p}{\epsilon^2} \int_{A_k} u_\epsilon(x) dx \geq -\frac{k^p}{\epsilon^2} e^{-\frac{k^p}{\epsilon^2}} =: a_k$$

and

$$\int_{B_k} u_\epsilon(x) \log u_\epsilon(x) \geq \int_{B_k} -\frac{k^p}{\epsilon^2} e^{-k^p/\epsilon^2} dx \geq -\frac{\pi^{\frac{n}{2}}}{\Gamma(\frac{n}{2} + 1)} k^n \frac{k^p}{\epsilon^2} e^{-\frac{k^p}{\epsilon^2}} =: b_k,$$

where $\Gamma(x)$ is the Gamma function.

It is easy to see that for any $l > 0$ there is an $\epsilon_0 > 0$ such that

$$\sum_{k=k_0}^{\infty} a_k + b_k \geq -\epsilon^l$$

for all $\epsilon \in (0, \epsilon_0)$. The proof is completed by letting $R_0 = k_0$. □

The second lemma bounds the integration of $u_\epsilon(x) \log u_\epsilon(x)$ over compact sets.

Lemma 4.2. *Let $v(x)$ be a probability density function on \mathbb{R}^n and $\Omega \subseteq \mathbb{R}^n$ be a Lebesgue measurable compact set. Then there is a $\delta_0 > 0$ such that for each $\delta \in (0, \delta_0)$, if*

$$\int_{\Omega} v(x) dx \leq \delta$$

then

$$\int_{\Omega} v(x) \log v(x) dx \geq -2\sqrt{\delta}.$$

Proof. The proof only contains elementary calculations. Let $\eta = \sqrt{\delta}$ and write Ω into $\Omega = A \cup B$, where $A = \{x \in \Omega : v(x) > e^{-1/\eta}\}$ and $B = \Omega \setminus A$. Then for every $\eta < 1$, we have

$$\int_A v(x) \log v(x) dx \geq -\frac{1}{\eta} \int_A v(x) dx \geq -\frac{\delta}{\eta}$$

and

$$\int_B v(x) \log v(x) dx \geq -\frac{1}{\eta} e^{-\frac{1}{\eta}} \int_B dx \geq -\frac{V}{\eta} e^{-\frac{1}{\eta}},$$

where V denotes the Lebesgue measure of Ω .

Let $\delta_0 = (\log V)^{-2}$. Then for any $\delta < \delta_0$, we have

$$\int_{\Omega} v(x) \log v(x) dx \geq -2\sqrt{\delta}.$$

□

The upper bound of $u_{\epsilon}(x)$ is estimated in the following lemma.

Lemma 4.3. *If \mathbf{H}^1 holds, then there is a constant $\epsilon_0 > 0$ such that $u_{\epsilon}(x) \leq \epsilon^{-2n+1}$ whenever $x \in \mathbb{R}^n$ and $\epsilon \in (0, \epsilon_0)$.*

Proof. We first show that there are positive constants p , ϵ_0 and $R_* < \infty$ independent of ϵ such that

$$(4.7) \quad u_{\epsilon}(x) \leq e^{-\frac{|x|^p}{2\epsilon^2}}$$

for every $|x| > R_*$ and $\epsilon \in (0, \epsilon_0)$.

It follows from \mathbf{H}^1) that there exist positive constants p , ϵ_* and R_0 such that

$$\mu_{\epsilon}(B(0, r)) \leq e^{-\frac{r^p}{\epsilon^2}}$$

for all $r > R_0$ and $\epsilon \in (0, \epsilon_*)$. For the sake of contradiction, we assume $u_{\epsilon}(x_0) > e^{-|x_0|^p/2\epsilon^2}$ for some $x_0 \in \mathbb{R}^n$ with $|x_0| > R_0 + 1$. It follows from Lemma 2.3 that there is a constant $C > 0$ such that for any ball $B(x_0, r)$ where $r < 1/4$, we have

$$\sup_{B(x_0, r)} u_{\epsilon} \leq C \inf_{B(x_0, r)} u_{\epsilon},$$

where $C = C_0(n)^{C_1 + \nu r \epsilon^{-2}}$, C_0 , C_1 and ν are constants independent of ϵ . Let $r = \epsilon^2$ and $C_* = C_0(n)^{C_1 + \nu}$. Then

$$(4.8) \quad \int_{B(x_0, r)} u_{\epsilon}(x) dx > \frac{\pi^{\frac{n}{2}}}{\Gamma(\frac{n}{2} + 1)} \frac{1}{C_*} \epsilon^{2n} e^{-\frac{|x_0|^p}{2\epsilon^2}}.$$

As ϵ approaches to 0, $e^{-\frac{|x_0|^p}{2\epsilon^2}}$ grows faster than any power of ϵ^{-1} . Hence one can make ϵ sufficient small such that

$$\int_{B(x_0, r)} u_{\epsilon}(x) dx > e^{-\frac{|x_0|^p}{\epsilon^2}}.$$

This contradicts with \mathbf{H}^1). Hence the claim holds for p , $R_0 = R_* + 1$ and some sufficiently small ϵ_0 .

Next we consider the upper bound of $u_\epsilon(x)$ within $B(0, R_*)$.

Assume, for the sake of contradiction, that $u_\epsilon(x_1) \geq \epsilon^{-(2n+1)}$ at some point $x_1 \in B(0, R_*)$. Apply Lemma 2.3 to $B(0, R_* + 1)$. We have that for any $x \in B(0, R_*)$ and $r \in (0, 1/4)$,

$$\sup_{B(x,r)} u_\epsilon \leq \hat{C} \inf_{B(x,r)} u_\epsilon,$$

where $\hat{C} = \hat{C}_0(n)\hat{C}_1 + \hat{\nu}r\epsilon^{-2}$, \hat{C}_0 , \hat{C}_1 and $\hat{\nu}$ are constants independent of ϵ and x .

Let $r = \epsilon^2$ and consider the neighborhood $B(x_1, r)$. By Lemma 2.3, we have

$$\min_{B(x_1,r)} u(x) \geq C_3 \epsilon^{-(2n+1)},$$

where constant C_3 is independent of ϵ . Thus, if $\epsilon^{-1} > C_3 \frac{\pi^{\frac{n}{2}}}{\Gamma(1+\frac{n}{2})}$, then

$$\mu_\epsilon(B(x_1, r)) > 1.$$

This contradicts with the fact that μ_ϵ is a probability measure. Therefore,

$$(4.9) \quad u_\epsilon(x) \leq \epsilon^{-(2n+1)}, \quad x \in B(0, R_*).$$

It now follows from (4.7) and (4.9) that $u_\epsilon(x)$ is globally bounded by ϵ^{-2n-1} for sufficient small $\epsilon > 0$. This completes the proof. \square

Now we are ready to prove Theorem 4.1.

Proof of Theorem 4.1. Let $\sigma \in (0, 1)$ be a small positive constant. Theorem 3.2 implies that there are constants $M, \epsilon_0 > 0$ such that

$$\mu_\epsilon(B(\mathcal{A}, M\epsilon)) \geq 1 - \sigma$$

for all $\epsilon \in (0, \epsilon_0)$.

Let

$$F(u_\epsilon) = \int_{B(\mathcal{A}, M\epsilon)} u_\epsilon(x) \log u_\epsilon(x) dx.$$

Applying Lagrange multiplier with constraint $\int_{B(\mathcal{A}, M\epsilon)} u_\epsilon dx = \mu_\epsilon(B(\mathcal{A}, M\epsilon))$, it is easy to see that $F(u_\epsilon)$ attains its minimum when u_ϵ is a constant function on $B(\mathcal{A}, M\epsilon)$. Thus

$$\begin{aligned} F(u_\epsilon) &\geq \int_{B(\mathcal{A}, C_2\epsilon)} u_a(x) \log u_a(x) dx \\ &\geq (1 - \sigma) \log \frac{1 - \sigma}{m(B(\mathcal{A}, C_2\epsilon))} \\ &= (1 - \sigma) \log(1 - \sigma) - (1 - \sigma) \log m(B(\mathcal{A}, M\epsilon)), \end{aligned}$$

where $u_a(x)$ is the constant function on $B(\mathcal{A}, M\epsilon)$ with value $\frac{\mu_\epsilon(B(\mathcal{A}, M\epsilon))}{m(B(\mathcal{A}, M\epsilon))}$.

The regularity of \mathcal{A} implies that

$$\lim_{r \rightarrow 0} \frac{\log m(B(\mathcal{A}, r))}{\log r} = n - d.$$

Thus

$$\lim_{\epsilon \rightarrow 0} \frac{\log m(B(\mathcal{A}, M\epsilon))}{\log \epsilon} = \lim_{\epsilon \rightarrow 0} \frac{\log m(B(\mathcal{A}, M\epsilon))}{\log M\epsilon} = n - d.$$

Next we estimate

$$\int_{\mathbb{R}^n \setminus B(\mathcal{A}, M\epsilon)} u_\epsilon(x) \log u_\epsilon(x) dx.$$

It follows from Lemmas 4.1 and 4.2 that there are positive constants R_* and ϵ_0 , such that for all $\epsilon \in (0, \epsilon_0)$, the integral of $u_\epsilon \log u_\epsilon$ on $B(0, R_*) \setminus B(\mathcal{A}, C_2\epsilon)$ and $\mathbb{R}^n \setminus B(0, R_*)$ are bounded from below by $-2\sqrt{\sigma}$ and $-\epsilon^2$ respectively. Thus

$$\int_{\mathbb{R}^n \setminus B(\mathcal{A}, M\epsilon)} u_\epsilon(x) \log u_\epsilon(x) dx \geq -\epsilon^2 - 2\sqrt{\sigma}$$

for $\epsilon \in (0, \epsilon_0)$.

Now, for any $0 < \sigma \ll 1$, some calculation shows that

$$\begin{aligned} \liminf_{\epsilon \rightarrow 0} \frac{\int_{\mathbb{R}^n} u_\epsilon(x) \log u_\epsilon(x) dx}{-\log \epsilon} &\geq \lim_{\epsilon \rightarrow 0} \frac{(1 - \sigma)(\log(1 - \sigma) - \log(m(B(\mathcal{A}, M\epsilon))))}{-\log \epsilon} - \frac{\epsilon^2 + 2\sqrt{\sigma}}{-\log \epsilon} \\ &= (1 - \sigma) \lim_{\epsilon \rightarrow 0} \frac{\log m(B(\mathcal{A}, M\epsilon))}{\log \epsilon} \\ &= (1 - \sigma)(n - d). \end{aligned}$$

Thus

$$\liminf_{\epsilon \rightarrow 0} \frac{\mathcal{H}(u_\epsilon)}{\log \epsilon} \geq n - d.$$

This completes the proof. \square

In general, the reversed inequality of (4.6)

$$(4.10) \quad \limsup_{\epsilon \rightarrow 0} \frac{\mathcal{H}(\mu_\epsilon)}{\log \epsilon} \leq n - d$$

for μ_ϵ cannot be shown by level set method. It can be shown by Theorem 3.3 and some calculation that for sufficient small $\epsilon > 0$ the integral of $u_\epsilon(x)$ on each level set $\Gamma_\rho(W)$ is bounded by ϵ^{-1} . However, the distributions of $u_\epsilon(x)$ on each of the level sets are not clear.

The theorem below gives some cases when (4.10) actually holds.

Theorem 4.2. *Assume \mathbf{H}^0) and \mathbf{H}^1) holds and the stationary measures μ_ϵ are regular with respect to \mathcal{A} . Then*

$$(4.11) \quad \lim_{\epsilon \rightarrow 0} \frac{\mathcal{H}(\mu_\epsilon)}{\log \epsilon} = n - d.$$

Proof. It follows from the definition of regular stationary measures with respect to \mathcal{A} that for any $\delta > 0$ there are positive constants K and ϵ_0 and a family of approximate functions $u_{K,\epsilon}$ such that $u_{K,\epsilon}$ approximates u_ϵ in the vicinity of \mathcal{A} . By the definition of regular stationary measures, there is a positive constant C independent of ϵ such that

$$\min(u_{K,\epsilon}(x)) \geq C \max(u_{K,\epsilon}(x)); \quad x \in B(\mathcal{A}, K\epsilon).$$

This means that

$$u_{K,\epsilon}(x) \leq \frac{C^{-1}}{m(B(\mathcal{A}, K\epsilon))}$$

for all $x \in B(\mathcal{A}, K\epsilon)$.

Let $u_1 = u_\epsilon - u_{K,\epsilon}$. Then by the convexity of $x \log x$, we have

$$\begin{aligned}
 & \int_{\mathbb{R}^n} u_\epsilon(x) \log u_\epsilon(x) dx = \int_{\mathbb{R}^n} (u_{K,\epsilon}(x) + u_1(x)) \log(u_{K,\epsilon}(x) + u_1(x)) dx \\
 & \leq \int_{\mathbb{R}^n} (u_{K,\epsilon}(x) + |u_1(x)|) \log(u_{K,\epsilon}(x) + |u_1(x)|) dx + 2 \int_{\mathbb{R}^n} |u_1(x)| |\log(u_{K,\epsilon}(x) + |u_1(x)|)| dx \\
 & = 2 \int_{\mathbb{R}^n} \frac{u_{K,\epsilon}(x) + |u_1(x)|}{2} \log \frac{u_{K,\epsilon}(x) + |u_1(x)|}{2} dx + 2 \int_{\mathbb{R}^n} |u_1(x)| |\log(u_{K,\epsilon}(x) + |u_1(x)|)| dx + \log 2 \\
 & \leq \int_{\mathbb{R}^n} u_{K,\epsilon}(x) \log u_{K,\epsilon}(x) dx + \int_{\mathbb{R}^n} |u_1(x)| \log |u_1(x)| dx + 2 \int_{\mathbb{R}^n} |u_1(x)| |\log(u_{K,\epsilon}(x) + |u_1(x)|)| dx + \log 2 \\
 & := \int_{\mathbb{R}^n} u_{K,\epsilon}(x) \log u_{K,\epsilon}(x) dx + I_1
 \end{aligned}$$

It follows from Lemma 4.3 that $u_\epsilon(x)$ is bounded from above by ϵ^{-2n-1} globally, so are $u_{K,\epsilon}$ and u_1 . Hence we have

$$I_1 \leq 3(2n+1)(-\log \epsilon)\delta + \log 2.$$

Take the limit $\epsilon \rightarrow 0$. The regularity of \mathcal{A} and the upper bound of $u_{K,\epsilon}$ together yield that

$$\limsup_{\epsilon \rightarrow 0} \frac{\mathcal{H}(\mu_\epsilon)}{\log \epsilon} = \limsup_{\epsilon \rightarrow 0} \frac{\int_{\mathbb{R}^n} u_\epsilon(x) \log u_\epsilon(x) dx}{-\log \epsilon} \leq n - d + 3\delta(2n+1).$$

The above inequality holds for any $\delta > 0$. Hence

$$\limsup_{\epsilon \rightarrow 0} \frac{\mathcal{H}(\mu_\epsilon)}{\log \epsilon} \leq n - d.$$

Combining this with Theorem 4.1, the proof is completed. \square

Remark 4.1. The entropy-dimension inequality and entropy-dimension equality will be used in the second part of the series when we discuss the properties of degeneracy and complexity.

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